# Multi-level Monte Carlo for System Reliability Simulation

#### Tigran Nagapetyan, Louis J. M. Aslett and Sebastian J. Vollmer

#### Department of Statistics, University of Oxford

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## Outline

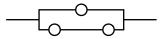
#### Introduction

- Simulating system lifetimes
- Recap standard Monte Carlo methods
- 2 Multi-level Monte Carlo (MLMC)
  - Introduction to MLMC for reliability audience
- **3** MLMC for reliability
  - Level grouping criterion
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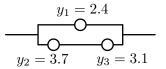
4 Future work

# Introduction

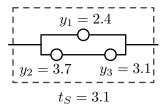
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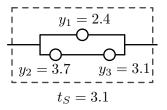
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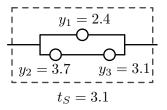


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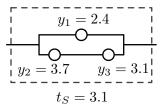
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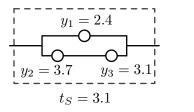
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Future work

## Simulating system lifetimes

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#### Monte Carlo simulation (I)

To estimate the expectation of some functional of the system lifetime,  $\mu = \mathbb{E}[f(T_S)]$ , simply perform Monte Carlo simulation:

$$\mathbb{E}[f(T_S)] \approx \hat{I}_n \triangleq \frac{1}{n} \sum_{j=1}^n f(T_S^{(j)})$$
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We know that,

$$\mathbb{P}\left(|\hat{I}_n - \mu| > z \frac{\sigma}{\sqrt{n}}\right) \approx \mathbb{P}(|Z| > z)$$

for  $Z \sim N(0, 1)$ , with  $\hat{I}_n$  an unbiased estimate of  $\mu$ .

#### Monte Carlo simulation (II)

Thus, for a desired level of accuracy  $\varepsilon > 0$  with  $\alpha\%$  confidence, we require

$$n = z_{lpha/2}^2 \sigma^2 \varepsilon^{-2}$$

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 $z_{\alpha/2}$  constant for a given confidence, so the variable compute cost in simulation can be defined as

$$\operatorname{Cost}_{MC} = \sigma^2 \varepsilon^{-2} |\mathcal{C}|$$

Costly for:

- High accuracy (small  $\varepsilon$ )
- Large systems (many cutsets)
- Large system lifetime variance

# Trying to cheat ...

May want to try getting a coarser estimate.

$$\mathcal{C}' \subset \mathcal{C} \implies \min_{C \in \mathcal{C}'} \{ \max_{i \in C} \{ y_i \} \} = t'_S \ge t_S = \min_{C \in \mathcal{C}} \{ \max_{i \in C} \{ y_i \} \}$$

But now,  $\hat{I}'_n$  is a biased estimate of  $\mu$ . Let  $\hat{I}'_n \rightarrow \eta$ , then:

$$\mathbb{E}\left[(\hat{I}'_n - \mu)^2\right] = \mathbb{E}\left[(\hat{I}'_n - \eta + \eta - \mu)^2\right]$$
$$= \mathbb{E}\left[(\hat{I}'_n - \eta)^2\right] + (\eta - \mu)^2$$
$$= \frac{\sigma^2}{n} + (\eta - \mu)^2$$

so that the error is composed of contributions from both the coarse approximation variance and the bias in the estimate.

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MLMC grew out of stochastic partial differential equation applications where simulations are so expensive that performing enough to reduce Monte Carlo variance to acceptable levels was impractical.

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Can we use MLMC in combination with an approximation arising from evaluation of subsets of the minimal cutsets?

## Lightning introduction to MLMC (I)

Assume have L + 1 *levels* of accuracy with which we can simulate system failure time,  $T_0, \ldots, T_L \equiv T_S$ , with level L being equivalent to standard Monte Carlo<sup>1</sup>.

Here,  $T_0, \ldots, T_L$  is the estimate based on a nested sequence of cutsets,  $C_0 \subset \cdots \subset C_L = C$ .

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Then, a telescoping sum can be formed:

$$\mathbb{E}[T_{\mathcal{S}}] \equiv \mathbb{E}[T_0] + \sum_{l=1}^{L} \mathbb{E}[T_l - T_{l-1}]$$

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In a nut shell, this identity provides an estimator with same expected value as standard Monte Carlo ... but, for a fixed variance (fixed accuracy) has much lower computational cost.

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### Lightning introduction to MLMC (II)

Independently estimate each term. Crucially, within each term,  $T_l$  and  $T_{l-1}$  use the same random component simulations:

$$\mathbb{E}[T_{l} - T_{l-1}] \approx N_{l}^{-1} \sum_{j=1}^{N_{l}} \left( t_{l}^{(j)} - t_{l-1}^{(j)} \right)$$

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$$\operatorname{Var}\left(\sum_{l=0}^{L} \mathbb{E}[T_{l} - T_{l-1}]\right) = \sum_{l=0}^{L} N_{l}^{-1} \sigma_{l}^{2}$$

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Hence, given a target fixed variance (accuracy), taking for each level  $N_l \propto \frac{\sigma_l}{\sqrt{|C_l|}}$  will minimise the computational cost.

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For a desired accuracy  $\varepsilon >$  0, this leads to an overall cost:

$$Cost_{ML} = \sum_{l=0}^{L} N_l |\mathcal{C}_l|$$
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Recall,

$$\mathsf{Cost}_{MC} = \sigma^2 \varepsilon^{-2} |\mathcal{C}| \triangleq \sigma^2 \varepsilon^{-2} |\mathcal{C}_L|$$

So,  $\sigma_l$  must decay in order for MLMC to be at MC.

See Giles (2015) for deeper review.

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How do we choose?

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- The mean of each level decaying rapidly is desirable so that each additional term has little influence.
- By the same argument, we want level 0 to be the best estimate possible since it will have smallest cost and be repeated most.

# Setup

Some notation:

- Let  $\mathcal{C} \triangleq \{C_1, \ldots, C_M\}.$
- Let there be *K* components, with lifetimes  $\underline{\tau} = (\tau_1, \ldots, \tau_K)$ .
- Let  $C_i(\underline{\tau}) \triangleq \max_{j \in C_i} \{\tau_j\}.$
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To achieve geometric growth in cost we will aim for approx doubling of the number of cutsets in each level. For example, M = 1000, take:

$$|C_7| = 1000$$
  
 $|C_6| = 500$   
 $|C_5| = 250$   
 $\vdots$   
 $|C_0| = 8$ 

#### Selecting the levels, l = 0

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- **6** Set  $C_0 = \{C_{(1)}, \ldots, C_{(m_0)}\}$  where  $m_0 = \lceil 2^{-L}(|\mathcal{C}| 1) + 1 \rceil$ .

This provides a crude estimate of the most common failure cause cutsets.

For the remaining levels, note that we want

$$\mathbb{E}[T_l - T_{l-1}] > \mathbb{E}[T_{l+1} - T_l]$$

Therefore, having chosen level l - 1,  $C_{l-1}$ , want level l st

 $\mathbb{E}[T_{l-1} - T_l] \to \max$ 

Future work

## Selecting the levels, l > 0 (I)

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But,

$$\mathbb{E}[T_{l-1} - T_l] \leq \mathbb{E}\Big[T_{l-1} - \min\left\{T_{l-1}, \max_{C \in \mathcal{C} \setminus \mathcal{C}_{l-1}} C(\underline{\tau})\right\}\Big]$$

We will attempt to crudely achieve this ordering using the 100 simulations already done.

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**1** Reindex remaining cutsets in  $C \setminus C_{l-1}$  from 1 to  $M - m_{l-1}$ .

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- 2 Compute

$$\delta_i = 0.01 \sum_{j=1}^{100} \left[ T_{l-1} - \min \left\{ C_i(\underline{\tau}^{(j)}), T_{l-1} \right\} \right] \quad \forall i = 1, \dots, M - m_{l-1}$$

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**3** Sort cutsets by order statistic of  $\delta_i$ ,  $(C_{(1)}, \ldots, C_{(M-m_{l-1})})$ 

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**3** Sort cutsets by order statistic of  $\delta_i$ ,  $(C_{(1)}, \ldots, C_{(M-m_{l-1})})$  **4** Set  $C_l = C_{l-1} \cup \{C_{(1)}, \ldots, C_{(m_l)}\}$  where  $m_l = \lceil 2^{-L+l}(|\mathcal{C}| - 1) + 1 \rceil - m_{l-1}.$ 

Finally, with the levels all selected, set a desired precision  $\varepsilon>0$  and proceed:

1 Initially set  $N_l = 100$  for l = 0, ..., 3 and simulate these levels

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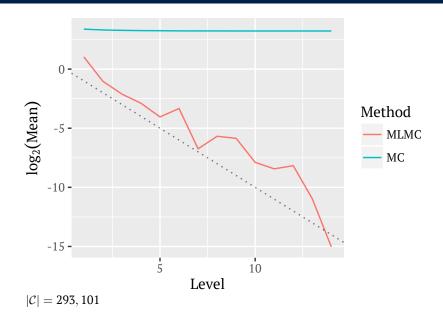
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- **3** Compute additional number of iterations,  $N_l$ , at each level to achieve  $\varepsilon$  precision. Repeat 2 until less than 1% growth in  $N_l \forall l$ .

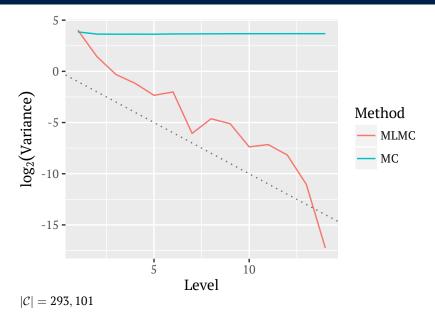
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- **3** Compute additional number of iterations,  $N_l$ , at each level to achieve  $\varepsilon$  precision. Repeat 2 until less than 1% growth in  $N_l \forall l$ .
- Variance has converged, now test bias. If bias within tolerance end, otherwise add a new level and return to 2.

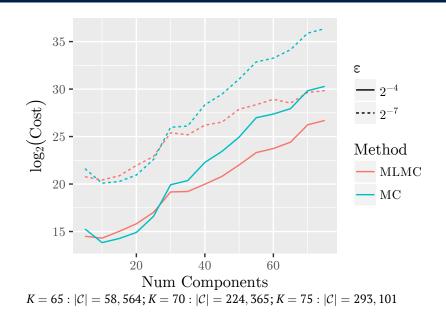
## Mean plot — 75 different Weibull components



# Variance plot — 75 different Weibull components



### Cost plot — all different Weibull components



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## Future work

## Open questions ...

Many possible directions:

- Estimation of the full system lifetime distribution (Giles 2015)
- Use MLMC with a survival signature based simulation in the independent/exchangeable case (?)
- Preserving privacy of component lifetimes can MLMC provide enough efficiency for private simulation (?)

#### **References I**

Giles, M. B. (2008). Multilevel monte carlo path simulation. *Operations Research*, 56/3: 607–17. INFORMS. Giles, M. B. (2015). Multilevel monte carlo methods. Acta *Numerica*, 24: 259–328. Cambridge Univ Press. Giles, M. B., Nagapetyan, T., & Ritter, K. (2015). Multilevel monte carlo approximation of distribution functions and densities. SIAM/ASA Journal on Uncertainty Ouantification, 3/1: 267-95. SIAM. Heinrich, S. (1998). Monte carlo complexity of global solution of integral equations. Journal of Complexity, 14/2: 151–75. Elsevier.