

Compressed M-SIDH: An Instance of Compressed SIDH-like Schemes with Isogenies of Highly Composite Degrees

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Abstract. Recently, SIDH was broken by a series of attacks. To avoid the attacks, several new countermeasures, such as M-SIDH and binSIDH, have been developed. Different from SIDH, the new SIDH-like schemes have relatively large public key sizes. Besides, the orders of the torsion groups considered in new SIDH-like schemes are the products of many primes. Therefore, the key compression techniques in SIDH can not be directly applied to these schemes. It remains an open problem to compress the public key in new SIDH-like schemes.

This paper takes M-SIDH as an instance to explore how to compress the public key in new SIDH-like schemes efficiently. We propose compressed M-SIDH, which is reminiscent of compressed SIDH. We also show that our approach to compress the public key of M-SIDH is valid and prove that compressed M-SIDH is secure as long as M-SIDH is secure. In addition, new algorithms to accelerate the performance of public-key compression in M-SIDH are presented in this paper.

We provide a proof-of-concept implementation of compressed M-SIDH in SageMath. Experimental results show that our approach fits well with compressed M-SIDH. The techniques proposed in this work also benefit public-key compression in other SIDH-like protocols, such as binSIDH and terSIDH. Besides, our method for torsion basis generation has the potential to improve the performance of SQALE and dCSIDH.

Keywords: M-SIDH · Post-quantum Cryptography · Public-key Compression · SIDH

1 Introduction

Since Supersingular Isogeny Diffie-Hellman (SIDH) [27] was proposed by Jao and De Feo, isogeny-based cryptosystems are attractive in post-quantum cryptography. As the NIST [2] round 4 finalist, Supersingular Isogeny Key Encapsulation (SIKE) [4] is famous for its small public key size.

To make SIDH/SIKE more attractive, a large variety of works target public-key compression in SIDH/SIKE to reduce the public key size. Public-key compression in SIDH was first proposed by Azarderakhsh et al. [5]. The key was further compressed by Costello et al. [17]. There are three main procedures in public-key compression in SIDH: torsion basis generation, pairing computation and discrete logarithm computation. Zanon et al. [45] utilized several techniques to accelerate the implementation significantly. Later, Naehrig and Renes [34] adapted the dual isogeny to speed up the performance of pairing computation, while Pereira, Doliskani and Jao [36] extended the work of [45] and gave a fast method to generate binary torsion basis. However, most of the techniques require large storage for precomputation. An efficient method to compute discrete logarithms with smaller lookup tables was proposed in [25]. Lin et al. [28] improved the Miller evaluation, making the implementation faster with less storage. Several works [29,35] also managed to compress the key using other approaches.

Recently, Castryck and Decru [11] proposed an efficient key recovery attack on SIDH and SIKE if the endomorphism ring of the starting curve is known. Maino et al. [31] gave a subexponential algorithm to attack SIDH with arbitrary starting curves. Inspired by these two works, Robert [40] presented a deterministic polynomial time attack on SIDH in all cases. The attacks also apply to Seta [20] and B-SIDH [16].

However, not all is lost. All the mentioned attacks entirely rely on the following information:

- the degree of the secret isogeny;
- the torsion point images.

Therefore, the attacks do not apply to a few SIDH-based schemes such as the isogeny-based Proof of Knowledge proposed in [19]. Furthermore, one could construct new schemes by hiding either of the above information to avoid the attacks. Moriya managed to hide the degree of the secret isogenies and proposed a new SIDH-like scheme, while Fouosta proposed another scheme, called M-SIDH (Masked torsion points SIDH), to avoid the attacks by masking auxiliary points [33,21,22]. However, to satisfy the desired security, both of SIDH-like schemes require relatively large parameter sizes, resulting in larger public key sizes compared with those of SIDH. Since the new isogeny degrees are the products of many prime factors, the approach to compress the public key of SIDH can not be directly extended to the case of new SIDH-like schemes. Therefore, how to compress the public key in new SIDH-like schemes is still an open problem.

In this paper, we give an approach to overcome this problem. We take M-SIDH as an instance and propose several new techniques to compress the public key of M-SIDH, whose size is $6 \log_2 p$ bits. This work is summarized as follows:

- We propose methods to compress the public key of M-SIDH. Reminiscent of compressed SIDH/SIKE, our method to compress the key also involves torsion basis generation, pairing computation and discrete logarithm computation. We prove that the problem underlying compressed M-SIDH is the

same as that of M-SIDH, and the key size is reduced from $6 \log_2 p$ bits to $4 \log_2 p$ bits.

- We propose several techniques to enhance the performance of compressed M-SIDH. Firstly, we propose a novel way to generate torsion basis. In particular, to determine whether two points can form a torsion basis we utilize compressed pairings and Lucas sequences. Secondly, an efficient approach is proposed for discrete logarithm computation. Finally, we utilize the Chinese Remainder Theorem to further compress the public key, reducing the key size to around $3.5 \log_2 p$ bits.
- We give the first instantiation of compressed M-SIDH in SageMath. Experimental results verify the validity of our algorithms.

It should be noted that our techniques also benefit other isogeny-based protocols. Our method can be applied to compress the public key of binSIDH and terSIDH [7]. For some non SIDH-like schemes, such as SQALE [14] and dC-SIDH [10], the technique to generate a full-torsion basis can also be utilized for speeding up their implementations.

Very recently, Castryck and Vercauteren [13] introduced a polynomial time attack to break M-SIDH when the initial (or end) curve is defined over the base field. This attack also applies to the case that the initial (or end) curve is connected to its Frobenius conjugate by a small degree isogeny. However, with overwhelming probability M-SIDH is still secure when the initial curve is generated by using an MPC protocol, which is proposed in [6]. Therefore, compressed M-SIDH is still secure as well.

The rest of this paper is as follows. In Section 2 we recall the reduced Tate pairing, compressed pairings, Lucas sequences, M-SIDH and public-key compression in SIDH/SIKE. Section 3 sketches our approach to compress the public key of M-SIDH and proves that compressed M-SIDH is secure if M-SIDH is secure. In Section 4 we present several novel techniques to compress the public key of M-SIDH efficiently. Section 5 reports our implementation and we conclude in Section 6.

2 Preliminaries

In this section, we first introduce the reduced Tate pairings, compressed pairings and Lucas sequences. Next, we recall M-SIDH. Finally, we review several techniques used in public-key compression in SIDH/SIKE.

2.1 Reduced Tate pairings

Let E be an elliptic curve over the finite field \mathbb{F}_q , where q is a power of a prime p . Let μ_n be the cyclic group of order n in \mathbb{F}_q^* with $n|q-1$, and $f_{n,R}$ to be a rational function on E satisfying $\text{div}(f_{n,R}) = n(R) - n(\mathcal{O})$, where $R \in E(\mathbb{F}_q)[n]$ and \mathcal{O} is the point at infinity. The reduced Tate pairing [23] is defined as:

$$e_n : E(\mathbb{F}_q)[n] \times E(\mathbb{F}_q)/nE(\mathbb{F}_q) \rightarrow \mu_n,$$

$$(R, S) \mapsto f_{n,R}(S)^{\frac{q-1}{n}}.$$

Similar with the Tate pairing [43], the reduced Tate pairing has the following properties:

- Bilinearity: $\forall R, R_1, R_2 \in E(\mathbb{F}_q)[n], \forall S, S_1, S_2 \in E(\mathbb{F}_q)/nE(\mathbb{F}_q),$

$$e_n(R, S_1 + S_2) = e_n(R, S_1) \cdot e_n(R, S_2),$$

$$e_n(R_1 + R_2, S) = e_n(R_1, S) \cdot e_n(R_2, S).$$

- Non-degeneracy: If $e_n(R, S) = 1$ for all $S \in E(\mathbb{F}_q)/nE(\mathbb{F}_q)$ then $R = \mathcal{O}$, and if $e_n(R, S) = 1$ for all $R \in E(\mathbb{F}_q)[n]$ then $S \in nE(\mathbb{F}_q)$.
- Compatibility with isogenies: Assume $\phi : E \rightarrow E'$ is a non-zero isogeny of degree m defined over \mathbb{F}_q . For $R \in E(\mathbb{F}_q)[n], S \in E(\mathbb{F}_q)/nE(\mathbb{F}_q), R' \in E'(\mathbb{F}_q)[n],$

$$e_n(\phi(R), \phi(S)) = e_n(R, S)^m,$$

$$e_n(R', \phi(S)) = e_n(\hat{\phi}(R'), S).$$

2.2 Compressed pairings and Lucas sequences

Compressed pairings were first introduced by Scott and Barreto [41]. This kind of pairings reduces the size of pairing values by replacing them with their traces. Assume that the elliptic curve is supersingular and it is defined over $\mathbb{F}_{p^2} = \mathbb{F}_p[i]/\langle i^2 + 1 \rangle$ with $p \equiv 3 \pmod{4}$ ³. In this case, computing the trace of the pairing value is more efficient than computing the pairing value itself.

The final exponentiation of pairings consists of a raising to the power of $p-1$ and the power of $(p+1)/n$. The former one is an easy part, but the latter requires relatively large computational resources. Thanks to Lucas sequences [18, Section 3.6.3], one can efficiently obtain $tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma^z)$ from $tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma)$ for $\gamma \in \mu_{p+1}$ and $z = (z_0 z_1 \cdots z_t)_2 \in \mathbb{N}$, as shown in Algorithm 1. Therefore, this technique can improve the costly part of the final exponentiation.

Lucas sequences have the potential to improve the exponentiation in the group μ_{p+1} as well. According to the observation in [41], for $\gamma = \gamma_1 + \gamma_2 \cdot i \in \mu_{p+1}$ and $z \in \mathbb{N}$,

$$(\gamma_1 + \gamma_2 \cdot i)^z = \frac{\text{LS}(\gamma, z)}{2} + \frac{\gamma_1 \cdot \text{LS}(\gamma, z) - \text{LS}(\gamma, z-1)}{2\gamma_1^2 - 2} \cdot \gamma_2 \cdot i.$$

Note that when computing $\text{LS}(\gamma, z-1)$, the explicit value of $\text{LS}(\gamma, z)$ is also obtained. When the inverse operation is not costly (for instance one can adapt the binary GCD algorithm) and z is large, utilizing Lucas sequences will improve the performance significantly. The main idea is summarized in Algorithm 2.

³ Indeed, the techniques proposed in this subsection also works when the elliptic curve is defined over \mathbb{F}_{q^2} , where q is a prime power.

Algorithm 1 LS: Lucas sequences

Require: $tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma)$ with $\gamma \in \mu_{p+1}$, $z = (z_0 z_1 \cdots z_t)_2 \in \mathbb{N}$;

Ensure: $tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma^z)$.

- 1: $v_0 \leftarrow 2, v_1 \leftarrow tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma), tmp \leftarrow v_1$;
 - 2: **for** each $j \in \{0, 1, \dots, t\}$ **do**
 - 3: **if** $z_j = 1$ **then**
 - 4: $v_0 \leftarrow v_0 \cdot v_1, v_0 \leftarrow v_0 - tmp, v_1 \leftarrow v_1^2, v_1 \leftarrow v_1 - 2$;
 - 5: **else**
 - 6: $v_0 \leftarrow v_0^2, v_0 \leftarrow v_0 - 2, v_1 \leftarrow v_0 \cdot v_1, v_1 \leftarrow v_1 - tmp$;
 - 7: **end if**
 - 8: **end for**
 - 9: **return** v_0 .
-

Algorithm 2 ELS: Exponentiation using Lucas sequences

Require: $\gamma = \gamma_1 + \gamma_2 \cdot i \in \mu_{p+1}, z \in \mathbb{N}_+$;

Ensure: γ^z .

- 1: $tmp_1 \leftarrow LS(\gamma, z), tmp_2 \leftarrow LS(\gamma, z - 1)$;
 //when computing $LS(\gamma, z - 1)$, $LS(\gamma, z)$ is also obtained
 - 2: $tmp_1 \leftarrow tmp_1/2, tmp_2 \leftarrow tmp_2/2$;
 - 3: $tmp_2 \leftarrow \gamma_1 \cdot tmp_1 - tmp_2, tmp_2 \leftarrow tmp_2/(\gamma_1^2 - 1), tmp_2 \leftarrow tmp_2 \cdot \gamma_2$;
 - 4: **return** $tmp_1 + tmp_2 \cdot i$.
-

2.3 M-SIDH

Let $p = 4 \cdot f \cdot \ell_1 \cdot \ell_2 \cdots \ell_t - 1$, where the primes $\ell_1, \ell_2, \dots, \ell_t$ are the first t odd primes and f is a small cofactor such that p is a prime. Denote $\ell_0 = 2$, $N_A = \ell_0 \cdot \ell_2 \cdots \ell_{t-1}$ and $N_B = \ell_1 \cdot \ell_3 \cdots \ell_t$. Define E_0 be a supersingular curve over \mathbb{F}_{p^2} together with $E_0[N_A] = \langle P_A, Q_A \rangle$ and $E_0[N_B] = \langle P_B, Q_B \rangle$. Similar to the SIDH protocol, M-SIDH proceeds as follows:

- Key Generation: Alice chooses a random integer $s_A \in \mathbb{Z}/N_A\mathbb{Z}$ as her secret key. She computes the point $P_A + [s_A]Q_A$ and constructs the N_A -isogeny ϕ_A with kernel $\langle P_A + [s_A]Q_A \rangle$. Then she evaluates two torsion point images $\phi_A(P_B), \phi_A(Q_B)$ and the image curve E_A . Finally, she transmits the tuple $(E_A, [a]\phi_A(P_B), [a]\phi_A(Q_B))$ to Bob, where $a \in \mu_2(N_B) = \{x \in \mathbb{Z}/N_B\mathbb{Z} \mid x^2 \equiv 1 \pmod{N_B}\}$. Similar to Alice, Bob selects a random integer $s_B \in \mathbb{Z}/N_B\mathbb{Z}$ to compute $P_B + [s_B]Q_B$ as the kernel generator of the N_B -isogeny ϕ_B . His public key is $(E_B, [b]\phi_B(P_A), [b]\phi_B(Q_A))$ with $b \in \mu_2(N_A) = \{x \in \mathbb{Z}/N_A\mathbb{Z} \mid x^2 \equiv 1 \pmod{N_A}\}$.
- Key Agreement: Alice begins her key agreement phase after receiving Bob's public key. She first checks whether $e_{N_A}([b]\phi_B(P_A), [b]\phi_B(Q_A))$ is equal to $e_{N_A}(P_A, Q_A)^{N_B}$, if not she aborts. Then she computes the point $[b]\phi_B(P_A) + [s_A]([b]\phi_B(Q_A))$ to construct the N_A -isogeny ϕ'_A with kernel $\langle \phi_B(P_A) + [s_A]\phi_B(Q_A) \rangle$ and regards the j -invariant $j(E_{BA})$ of the image curve as her shared key. Analogously, Bob checks whether $e_{N_B}([a]\phi_A(P_B), [a]\phi_A(Q_B))$ is

equal to $e_{N_B}(P_B, Q_B)^{N_A}$, if not he aborts. He computes the image curve E_{AB} of the N_B -isogeny ϕ'_B and the shared key $j(E_{AB})$.

The security of M-SIDH relies on the hardness of Problem 1:

Problem 1. Let $N_A = \ell_0 \ell_2 \cdots \ell_{t-1}$ and $N_B = \ell_1 \ell_3 \cdots \ell_t$ be two smooth integers, and f be a small cofactor such that $p = N_A N_B f - 1$ is a prime, with $N_A \approx N_B$. Let E_0/\mathbb{F}_{p^2} be a supersingular elliptic curve such that $\#E_0(\mathbb{F}_{p^2}) = (p+1)^2 = (N_A N_B f)^2$. Suppose that $E_0[N_A] = \langle P_A, Q_A \rangle$. Let $\phi_B : E_0 \rightarrow E_B$ be a uniformly random N_B -isogeny and let b be a uniformly random element of $\mu_2(N_A) = \{x \in \mathbb{Z}/N_A\mathbb{Z} \mid x^2 \equiv 1 \pmod{N_A}\}$.

Given $E_0, P_A, Q_A, E_B, [b]\phi_B(P_A), [b]\phi_B(Q_A)$, compute ϕ_B .

2.4 Public-key compression in SIDH/SIKE

In this subsection, we briefly review the main techniques utilized in public-key compression in SIDH/SIKE. For simplicity, we only consider how to compress the key $(E_B, \phi_B(P_A), \phi_B(Q_A))$.

The main idea of public-key compression is to deterministically generate a basis of the N_A -torsion group, and then use this basis to linearly represent $\phi_B(P_A)$ and $\phi_B(Q_A)$, i.e.,

$$\begin{bmatrix} \phi_B(P_A) \\ \phi_B(Q_A) \end{bmatrix} = \begin{bmatrix} a_0 & b_0 \\ a_1 & b_1 \end{bmatrix} \begin{bmatrix} U_A \\ V_A \end{bmatrix}. \quad (1)$$

After computing a_0, a_1, b_0 and b_1 , Bob checks whether a_0 is invertible in $\mathbb{Z}/N_A\mathbb{Z}^\times$. If so, Bob sends $(E_B, 0, a_0^{-1}b_0, a_0^{-1}a_1, a_0^{-1}b_1)$ to Alice. Otherwise, the element b_0 must be invertible in $\mathbb{Z}/N_A\mathbb{Z}^\times$ and Bob transmits $(E_B, 1, b_0^{-1}a_0, b_0^{-1}a_1, b_0^{-1}b_1)$ instead.

Assume that $a_0 \in \mathbb{Z}/N_A\mathbb{Z}^\times$, while the other case is similar. After receiving Bob's public key, Alice can compute the kernel of the isogeny ϕ'_A as follows [17]:

$$\begin{aligned} \langle \phi_B(P_A) + [s_A]\phi_B(Q_A) \rangle &= \langle [a_0]U_A + [b_0]V_A + [s_A a_1]U_A + [s_A b_0]V_A \rangle \\ &= \langle U_A + [a_0^{-1}b_0]V_A + [s_A a_0^{-1}a_1]U_A + [s_A a_0^{-1}b_0]V_A \rangle \\ &= \langle [1 + s_A(a_0^{-1}a_1)]U_A + [(a_0^{-1}b_0) + s_A(a_0^{-1}b_0)]V_A \rangle. \end{aligned}$$

Therefore, Alice can complete the key agreement phase without recovering $\phi_A(P_B)$ and $\phi_A(Q_B)$.

It remains how to obtain $a_0^{-1}b_0, a_0^{-1}a_1$ and $a_0^{-1}b_1$. Zanon et al. [45] proposed a new technique to speed up the performance. Since $\phi_B(P_A)$ and $\phi_B(Q_A)$ also form a basis of $E_B[N_A]$, they can also linearly represent U_A and V_A , i.e.,

$$\begin{bmatrix} U_A \\ V_A \end{bmatrix} = \begin{bmatrix} c_0 & d_0 \\ c_1 & d_1 \end{bmatrix} \begin{bmatrix} \phi_B(P_A) \\ \phi_B(Q_A) \end{bmatrix}. \quad (2)$$

It is easy to verify that

$$(a_0^{-1}b_0, a_0^{-1}a_1, a_0^{-1}b_1) = (-d_1^{-1}d_0/D, -d_1^{-1}c_1/D, d_1^{-1}c_0/D),$$

where $D = c_0d_1 - c_1d_0 \bmod N_A$. With the help of bilinear pairings,

$$\begin{aligned}
h_0 &= e_{N_A}(\phi_B(P_A), \phi_B(Q_A)) = e_{N_A}(P_A, Q_A)^{N_B}, \\
h_1 &= e_{N_A}(\phi_B(P_A), U_A) = e_{N_A}(\phi_B(P_A), c_0\phi_B(P_A) + d_0\phi_B(Q_A)) = h_0^{d_0}, \\
h_2 &= e_{N_A}(\phi_B(P_A), V_A) = e_{N_A}(\phi_B(P_A), c_1\phi_B(P_A) + d_1\phi_B(Q_A)) = h_0^{d_1}, \\
h_3 &= e_{N_A}(\phi_B(Q_A), U_A) = e_{N_A}(\phi_B(Q_A), c_0\phi_B(P_A) + d_0\phi_B(Q_A)) = h_0^{-c_0}, \\
h_4 &= e_{N_A}(\phi_B(Q_A), V_A) = e_{N_A}(\phi_B(Q_A), c_1\phi_B(P_A) + d_1\phi_B(Q_A)) = h_0^{-c_1}.
\end{aligned} \tag{3}$$

Note that h_0 only depends on public parameters. Therefore, one can recover c_0, c_1, d_0, d_1 by computing four discrete logarithms of h_1, h_2, h_3, h_4 to the base h_0 efficiently with precomputed lookup tables [45,25,34,28]. Another approach is to compute only three discrete logarithms of h_1, h_3, h_4 (resp. h_2, h_3, h_4) to the base h_2 (resp. h_1) [29]. Compared with the former method, the latter only needs to compute discrete logarithms, but the precomputation technique is not available since h_2 (resp. h_1) can not be computed in advance.

3 Public-key Compression in M-SIDH

In this section, we sketch our approach to compress the public key of M-SIDH and give Proposition 2 to show that compressed M-SIDH is secure if Problem 1 is hard.

3.1 Setup Modification

Different from the setup in M-SIDH, we make a minor modification of the parameters p, N_A and N_B for compressed M-SIDH. In our implementation, we set the parameter p as

$$p = 4 \cdot \ell_1 \cdot \ell_2 \cdots \ell_{t-1} \cdot \ell_t \cdot \ell_{t+1} - 1,$$

where $\ell_1, \ell_2, \dots, \ell_t$ are the first t odd primes, while the prime ℓ_{t+1} is slightly larger than ℓ_t such that p is a prime. Correspondingly, define $N_A = \ell_1 \cdot \ell_3 \cdots \ell_t$ and $N_B = \ell_2 \cdot \ell_4 \cdots \ell_{t+1}$.

Clearly, this modification does not affect the hardness of Problem 1. The main reason why we modify the parameters is to compress the public key with the help of the reduced Tate pairing correctly. We will give a more detailed explanation in the following. Another advantage of applying the reduced Tate pairing is that the pairing computation would be more efficient compared to the case when using the Weil pairing [32].

3.2 Our approach to compress the key

Our approach to compress the public key of M-SIDH is reminiscent of public-key compression in SIDH/SIKE. Given the tuple $(E_B, \phi_B(P_A), \phi_B(Q_A))$, a sketch of our approach to compress the key is as follows:

1. Torsion basis generation: deterministically generate $\{U_A, V_A\}$ such that $\langle U_A, V_A \rangle = E_B[N_A]$;
2. Pairing computation: Compute the following four reduced Tate pairings:

$$\begin{aligned} h_1 &= e_{N_A}(\phi_B(P_A), U_A), h_2 = e_{N_A}(\phi_B(P_A), V_A), \\ h_3 &= e_{N_A}(\phi_B(Q_A), U_A), h_4 = e_{N_A}(\phi_B(Q_A), V_A); \end{aligned} \quad (4)$$

3. Discrete logarithm computation: Compute discrete logarithms of h_i , $i = 1, 2, 3, 4$ to the base $h_0 = e_{N_A}(P_A, Q_A)^{N_B}$. Randomly select $b \in \mu_2(N_A)$ and then compute $s_i = b \cdot \log_{h_0}(h_i)$.

The compressed key is $(E_B, s_1, s_2, s_3, s_4)$. A question raised here is whether Equation (3) is correct in compressed M-SIDH when applying the reduced Tate pairing, because in general we do not have $e_{N_A}(P, P) = 1$ for every $P \in E_B(\mathbb{F}_{p^2})[N_A]$. Now we prove the following proposition to confirm that Equation (3) still holds in this situation.

Proposition 1. *Let E be a supersingular elliptic curve defined over \mathbb{F}_{p^2} with $p \equiv 3 \pmod{4}$. Suppose that N is odd and it divides $p+1$. Then $e_N(P, P) = 1$ for every $P \in E(\mathbb{F}_{p^2})[N]$.*

Proof. Since isogeny graphs for supersingular elliptic curves have the Ramanujan property [37], there exists an isogeny $\psi : E \rightarrow E'$ of degree 2^\bullet , where the elliptic curve $E' : y^2 = x^3 + x$ has j -invariant 1728. Since N is odd, we can deduce that $\psi(P)$ has order N for every $P \in E(\mathbb{F}_{p^2})[N]$. Therefore,

$$e_N(\psi(P), \psi(P)) = e_N(P, P)^{2^\bullet}.$$

This implies that $e_N(P, P) = 1$ for every $P \in E(\mathbb{F}_{p^2})[N]$ if and only if $e_N(P', P') = 1$ for every $P' \in E'(\mathbb{F}_{p^2})[N]$. In the following, we prove that $e_N(P', P') = 1$ for every $P' \in E'(\mathbb{F}_{p^2})[N]$.

From $E'(\mathbb{F}_p) \cong \mathbb{Z}/(p+1)\mathbb{Z}$, we can find a point $P_0 \in E'(\mathbb{F}_p)[N]$ of order N . Since the distortion map

$$\begin{aligned} \iota : E' &\rightarrow E', \\ (x, y) &\mapsto (-x, iy). \end{aligned}$$

is an isomorphism of E' such that P_0 and $\iota(P_0)$ are linearly independent. This implies that $\langle P_0, \iota(P_0) \rangle = E'(\mathbb{F}_{p^2})[N]$. Hence, for every P' there exist $r, s \in \mathbb{Z}/N\mathbb{Z}$ such that $P' = [r]P_0 + [s]\iota(P_0)$. As a consequence,

$$\begin{aligned} e_N(P', P') &= e_N([r]P_0 + [s]\iota(P_0), [r]P_0 + [s]\iota(P_0)) \\ &= e_N(P_0, P_0)^{r^2} e_N(P_0, \iota(P_0))^{rs} e_N(\iota(P_0), P_0)^{rs} e_N(\iota(P_0), \iota(P_0))^{s^2} \\ &= e_N(P_0, P_0)^{r^2} e_N(P_0, \iota(P_0))^{rs} e_N(P_0, \hat{\iota}(P_0))^{rs} e_N(P_0, P_0)^{\deg(\iota)s^2} \\ &= e_N(P_0, P_0)^{r^2 + \deg(\iota)s^2} e_N(P_0, \iota(P_0) + \hat{\iota}(P_0))^{rs}. \end{aligned}$$

Since the trace of ι is 0 and $\deg(\iota) = 1$, we have

$$e_N(P', P') = e_N(P_0, P_0)^{r^2+s^2} e_N(P_0, \mathcal{O})^{rs} = e_N(P_0, P_0)^{r^2+s^2}. \quad (5)$$

Note that $P_0 \in E'(\mathbb{F}_p)[N]$ and the final exponentiation is $(p-1) \cdot \frac{p+1}{N}$. Therefore, $e_N(P_0, P_0)$ is equal to 1. It follows from Equation (5) that $e_N(P', P') = 1$ for every $P' \in E'(\mathbb{F}_{p^2})[N]$, i.e., $e_N(P, P) = 1$ for every $P \in E(\mathbb{F}_{p^2})[N]$. This completes the proof.

From Proposition 1, it is easy to see that our method to compress the key is valid.

Corollary 1. *One can compress the public key by performing the above procedures.*

Remark 1. In the compressed SIDH protocol, it is impossible that none of h_i is a generator. However, it happens in compressed M-SIDH with small possibility. For example, in Equation (2) the prime ℓ_2 may divide c_0 and d_1 , while ℓ_4 may divide d_0 and c_1 . This is the reason why Bob needs to compute four discrete logarithms to the base h_0 instead of computing three discrete logarithms to one of h_i . In addition, it is possible that none of s_i is invertible in $\mathbb{Z}/N_A\mathbb{Z}$. Hence, we can not further compress the key by directly applying the technique proposed by Costello et al. [17, Section 6]. In Section 4.3, we will propose a method to overcome this issue, compressing the key size from $4 \log_2 p$ bits to around $3.5 \log_2 p$ bits.

Remark 2. As mentioned in Section 1, one can utilize dual isogenies to optimize pairing computation [34,28] in compressed SIDH. However, the dual isogeny construction in compressed M-SIDH is much more costly compared to that of compressed SIDH. According to our experiments, directly computing h_1, h_2, h_3 and h_4 in Equation (4) without the dual isogeny technique is more efficient. Therefore, we do not utilize the dual isogeny technique in our implementation.

In the following, we show that compressed M-SIDH is secure as long as Problem 1 is hard.

Proposition 2. *Compressed M-SIDH is secure if Problem 1 is hard.*

Proof. Without loss of generality, we only consider Bob's case, while the other case is similar. Obviously, from the compressed key one can deduce that

$$\begin{bmatrix} [b]\phi_B(P_A) \\ [b]\phi_B(Q_A) \end{bmatrix} = \frac{1}{D} \begin{bmatrix} s_2 - s_1 \\ s_4 - s_3 \end{bmatrix} \begin{bmatrix} U_A \\ V_A \end{bmatrix}.$$

where $D = s_1 s_4 - s_2 s_3 \pmod{N_A}$ and $b \in \mu_2(N_A)$ is unknown. Conversely, given the uncompressed key $(E_B, [b]\phi_B(P_A), [b]\phi_B(Q_A))$ where b is unknown, one can compress it by adapting the procedures we proposed above. Therefore, compressed M-SIDH is secure as long as M-SIDH is secure, i.e., Problem 1 is hard.

4 Optimizations on Compressed M-SIDH

To avert the attacks proposed in [11,31,40], M-SIDH requires two large scalar multiplications of length $\approx \sqrt{p}$, while compressed M-SIDH avoids this procedure.

Instead, we compute $s_i = b \cdot \log_{h_0}(h_i)$, $i = 1, 2, 3, 4$ to mask the torsion points. However, it should be noted that the performance of compressed M-SIDH is still not as efficient as that of M-SIDH because of torsion basis generation, pairing computation and discrete logarithm computation. In this section we will optimize the performance of key compression to close the gap. As before, we only handle Bob's case and Alice can also adapt all the techniques to accelerate the performance.

4.1 Torsion basis generation

Since N_A and N_B are not the power of 2 and 3, torsion basis generation in compressed M-SIDH can not benefit from several techniques such as shared Elligator [45] and 3-descent of elliptic curves [17]. In this subsection we propose a new method to deterministically generate $\{U_A, V_A\}$ such that $\langle U_A, V_A \rangle = E_B[N_A]$, while torsion basis generation of the N_B -torsion group of E_A is similar. Note that some of the results proposed in this section rely on the fact that N_A is squarefree. For simplicity, we abbreviate U_A and V_A to U and V , respectively.

Generating one of the torsion points is relatively easy: we can deterministically choose a point of order N_A and then set it as U . After U is successfully generated, we deterministically generate another point V such that $\langle U, V \rangle = E_B[N_A]$.

As for the first torsion point, a naive way is to deterministically sample a point $R \in E_B(\mathbb{F}_{p^2})$, and then check whether the order of $[4N_B]R$ is N_A . Here we propose Algorithm 3 to generate U , which is more efficient than the naive approach. We also output $\{U_j | j \in I\}$ with $I = \{j | \ell_j \text{ divides } N_A\}$, which is useful for the generation of the second torsion point V .

Algorithm 3 GenerationU: deterministically generate a point of order N_A

Require: E_B/\mathbb{F}_{p^2} : a supersingular curve, $I : \{j | \ell_j \text{ divides } N_A\}$;

Ensure: A point $U \in E_B(\mathbb{F}_{p^2})$ of order N_A , $\{U_j | j \in I\}$.

- 1: Deterministically generate a point $R \in E_B(\mathbb{F}_{p^2})$ using Elligator;
 - 2: $U \leftarrow [4N_B]R$;
 - 3: $\{U_j\} \leftarrow \text{BCM}(U, I)$; // Algorithm 4
 - 4: $I_U \leftarrow \{j | U_j = \mathcal{O}\}$;
 - 5: **while** $I_U \neq \emptyset$ **do**
 - 6: Deterministically generate a point $R \in E_B(\mathbb{F}_{p^2})$ using Elligator;
 - 7: $U' \leftarrow [4N_B]R$;
 - 8: $U' \leftarrow [\prod_{j \in I \setminus I_U} \ell_j]U'$;
 - 9: $\{U'_j\} \leftarrow \text{BCM}(U', I_U)$; // Algorithm 4
 - 10: **for** each $j \in \{k | U'_k \neq \mathcal{O}\}$ **do**
 - 11: $U \leftarrow U + U'_j$, $U_j \leftarrow U'_j$;
 - 12: **end for**
 - 13: $I_U \leftarrow \{j | U'_j = \mathcal{O}\}$;
 - 14: **end while**
 - 15: **return** U , $\{U_j | j \in I\}$.
-

The main idea of Algorithm 3 is as follows.

Firstly, we deterministically generate a point R using Elligator [9] and set $U = [4N_B]R$.

Next, we use Algorithm 4 to compute $U_j = [N_A/\ell_j]U$, where $j \in I = \{j|\ell_j \text{ divides } N_A\}$. Since N_A is squarefree, it is easy to see that U_j is a point of order ℓ_j if ℓ_j divides the order of U . Otherwise, U_j is the point at infinity.

Denote $I_U = \{j|U_j = \mathcal{O}\}$. If I_U is not empty, we deterministically sample another point R and compute $U' = [4N_B]R$. According to I_U , we compute $U'_j = [N_A/\ell_j]U'$ where $j \in I_U$. If U'_j is not the point at infinity, set $U = U + U'_j$. Finally, let $I_U = \{j|U'_j = \mathcal{O}\}$. We repeat the above progress to generate U' until I_U is empty. As a result, for each $j \in I$ we have $U_j \neq \mathcal{O}$. Therefore, U is a point of order N_A .

Remark 3. The approach to compute U_j is inspired by the public-key validation of CSIDH [12]. The authors check the key by generating a point and then check the order of the point using a divide-and-conquer approach [42]. Although this approach consumes slightly larger memory, it performs more efficient than directly computing each U_j .

Algorithm 4 BCM: Batch cofactor multiplication

Require: U : a point on $E_B[N_A]$, I_U : a subset of $I = \{j|\ell_j \text{ divides } N_A\}$;

Ensure: $\{U_k|k \in I_U\}$, where $U_k = [\prod_{j \in I_U \setminus \{k\}} \ell_j]U$.

- 1: $n' \leftarrow \#I_U$;
 - 2: **if** $n' = 1$ **then**
 - 3: **return** $\{U\}$;
 - 4: **end if**
 - 5: $m' \leftarrow \lfloor n'/2 \rfloor$;
 - 6: Divide I_U into two subsets I_1, I_2 such that $\#I_1 = n' - m'$ and $\#I_2 = m'$;
 - 7: $L_1 \leftarrow \prod_{i \in I_2} \ell_i$, $L_2 \leftarrow \prod_{i \in I_1} \ell_i$;
 - 8: $left \leftarrow [L_1]U$;
 - 9: $right \leftarrow [L_2]U$;
 - 10: $r_1 \leftarrow \text{BCM}(left, I_1)$;
 - 11: $r_2 \leftarrow \text{BCM}(right, I_2)$;
 - 12: **return** $r_1 \cup r_2$.
-

In the following we focus on how to deterministically generate another point V such that $\langle U, V \rangle = E_B[N_A]$. A naive approach is to generate V with respect to the above method, and then check if U and V can generate the N_A -torsion group. However, this method is not so practical because the success probability is relatively small. Here we present a more efficient method to generate V thanks to Proposition 3.

Proposition 3. *Assume that U is a point of order $N_A = \ell_1 \ell_3 \cdots \ell_t$ on E_B , and V a point on $E_B(\mathbb{F}_{p^2})$. Let $I = \{j|\ell_j \text{ divides } N_A\}$, $U_k = [\prod_{j \in I \setminus \{k\}} \ell_j]U$. Denote*

by $\text{ord}(\gamma)$ the order of γ in μ_{N_A} . Then

$$\text{ord}(e_{N_A}(U, V)) = \prod_{\substack{j \in I \\ e_{\ell_j}(U_j, V) \neq 1}} \ell_j. \quad (6)$$

In particular, $e_{N_A}(U, V)$ is a generator of μ_{N_A} if and only if $\langle U, V \rangle = E_B[N_A]$.

Proof. Let $s_k = \prod_{j \in I \setminus \{k\}} \ell_j$ and $s'_k = s_k^{-1} \bmod \ell_k$. From $U_k = [\prod_{j \in I \setminus \{k\}} \ell_j]U$ we have $U = \sum_{k \in I} [s'_k]U_k$. Utilizing the bilinearity of the reduced Tate pairing,

$$\begin{aligned} & e_{N_A}(U, V) \\ &= e_{N_A}([s'_1]U_1, V) \cdot e_{N_A}([s'_3]U_3, V) \cdots e_{N_A}([s'_t]U_t, V) \\ &= e_{N_A}(U_1, V)^{s'_1} \cdot e_{N_A}(U_3, V)^{s'_3} \cdots e_{N_A}(U_t, V)^{s'_t}. \end{aligned} \quad (7)$$

From [24, Theorem IX.9], we have

$$e_{N_A}(U_k, V) = e_{\ell_k}(U_k, V).$$

Let $V_k = [\prod_{j \in I \setminus \{k\}} \ell_j]V$. Obviously, $e_{\ell_k}(U_k, V) = 1$ if and only if $e_{\ell_k}(U_k, V_k) = 1$.

In the following, we will prove that V_k and U_k are linearly dependent if and only if $e_{\ell_k}(U_k, V_k) = 1$, i.e., $e_{N_A}(U_k, V) = 1$.

We first assume that V_k and U_k are linearly dependent. Then we have

- $V_k = \mathcal{O}$, or
- $V_k \neq \mathcal{O}$, but $V_k \in \langle U_k \rangle$,

and *vice versa*. It follows from Proposition 1 that $e_{\ell_k}(U_k, V_k) = 1$. Conversely, if V_k and U_k are linearly independent, we can easily deduce that $e_{N_A}(U_k, V) \neq 1$ from the non-degeneracy of the reduced Tate pairing. In this case, $e_{N_A}(U_k, V)$ is a generator of the group μ_{ℓ_k} .

It is clear that $e_{N_A}(U_k, V) \neq 1$ if and only if $e_{N_A}(U_k, V)^{s'_k} \neq 1$. According to Equation (7), the order of $e_{N_A}(U, V)$ depends on the order of each $e_{N_A}(U_k, V)$:

$$\text{ord}(e_{N_A}(U, V)) = \prod_{k \in I} \text{ord}\left(e_{N_A}(U_k, V)^{s'_k}\right) = \prod_{k \in I} \text{ord}(e_{N_A}(U_k, V)).$$

If $e_{N_A}(U_k, V)$ is not equal to 1, then $e_{N_A}(U, V)$ has order divisible by ℓ_k . Otherwise, we know that ℓ_k does not divide the order of $e_{N_A}(U, V)$. Consequently, we have Equation (6).

If $e_{N_A}(U, V)$ is a generator of μ_{N_A} , for each k we have $e_{\ell_k}(U_k, V_k) \neq 1$, thus U_k and V_k are linearly independent. It follows that $\langle U_k, V_k \rangle = E_B[\ell_k]$ for each k . It should be noted that

$$E_B[N_A] \cong E_B[\ell_1] \oplus E_B[\ell_3] \oplus \cdots \oplus E_B[\ell_t]. \quad (8)$$

Therefore, $\langle U, V \rangle = E_B[N_A]$. Suppose that $\langle U, V \rangle = E_B[N_A]$, and now we are going to prove $e_{N_A}(U, V) \in \mu_{N_A}$ is of order N_A . Assume that ℓ_k does not divide the order of $e_{N_A}(U, V) \in \mu_{N_A}$. Then

$$e_{N_A}(U, V)^{N_A/\ell_k} = e_{N_A}([N_A/\ell_k]U, V) = e_{N_A}(U_k, V) = e_{\ell_k}(U_k, V_k) = 1.$$

This induces $\langle U_k, V_k \rangle \cong \mathbb{Z}/\ell_k\mathbb{Z}$. From Equation (8), we can deduce that $\{U, V\}$ is not the torsion basis of $E_B[N_A]$, which is a contradiction. This completes the proof.

Proposition 3 gives an approach to test whether two points generate the torsion group $E_B[N_A]$ by checking the order of the pairing value in the group μ_{N_A} . One can deterministically generate a point $V \in E_B(\mathbb{F}_{p^2})[N_A]$ using Elligator, and compute the order of $e_{N_A}(U, V)$ in μ_{N_A} . Then we have a subset $I_V = \{j_k | e_{\ell_{j_k}}(U_{j_k}, V) = 1\}$ of the set $I = \{j | \ell_j \text{ divides } N_A\}$. Similar to the method to deterministically generate the point U , we deterministically generate another point $V' \neq V$ and compute:

$$f' = e_{\prod_{j_k \in I_V} \ell_{j_k}} \left(\sum_{j_k \in I_V} U_{j_k}, \left[\prod_{j \in I \setminus I_V} \ell_j \right] V' \right). \quad (9)$$

After that, we check whether ℓ_{j_k} divides the order of $f' \in \mu_{N_A}$ for each $j_k \in I_V$. If so, set $V = V + V'_{j_k}$, where $V'_{j_k} = [N_A/\ell_{j_k}]V'$. We deterministically generate another new point V' and repeat the procedure until the set $I_V = \{j_k | e_{\ell_{j_k}}(U_{j_k}, V') = 1\}$ is empty. Finally, we have a point V such that $e_{N_A}(U, V)$ is a generator of μ_{N_A} , then $\langle U, V \rangle = E_B[N_A]$ according to Proposition 3.

It seems that once we would like to generate V , we need to deterministically generate a point R on $E(\mathbb{F}_q)$ and then perform a large scalar multiplication $V = [4N_B]R$ such that $\text{ord}(V) | N_A$. Fortunately, this large scalar multiplication is not necessary when just computing $\text{ord}(e_{N_A}(U, V))$. It is obvious that $4N_B$ and N_A are coprime and therefore,

$$\text{ord}(e_{N_A}(U, V)) = \text{ord}\left((e_{N_A}(U, R))^{4N_B}\right) = \text{ord}(e_{N_A}(U, R)).$$

It confirms that we can just deterministically generate a point $R \in E(\mathbb{F}_q)$ to compute $\text{ord}(e_{N_A}(U, V)) = \text{ord}(e_{N_A}(U, R))$. For the same reason we can save the scalar multiplication of V' in Equation (9) as well.

Checking the order of the pairing value is also a costly step. Indeed, the aim of the pairing computation is not to compute the precise pairing value but its order. Here we give a lemma, which allows us to compute compressed pairings to reach the goal.

Lemma 1. *If $\gamma \in \mu_{p+1} = \{x \in \mathbb{F}_{p^2} | x^{p+1} = 1\}$ with $\mathbb{F}_{p^2} \cong \mathbb{F}_p[i]/\langle i^2 + 1 \rangle$ and $p \equiv 3 \pmod{4}$, then $\gamma = 1$ if and only if $\text{tr}_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma) = 2$.*

Proof. The necessity is obvious. Now we show the sufficiency. Suppose that $\gamma = \gamma_1 + \gamma_2 \cdot i$. From $\text{tr}_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\gamma) = 2$, we have $2\gamma_1 = 2$ and hence $\gamma_1 = 1$. Since $\gamma \in \mu_{p+1}$, $\gamma^{p+1} = \gamma_1^2 + \gamma_2^2 = 1$. It implies that $\gamma_2 = 0$.

Therefore, to check the order of the pairing value f' , one can first compute $tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(f')$, and then utilize Lucas sequences to obtain $tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}((f')^{N_A/\ell_k})$ for each $k \in I_V$. Similar to Algorithm 4, we present Algorithm 5 to compute them efficiently.

Algorithm 5 BCE: Batch cofactor exponentiation

Require: $f' \in tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}(\mu_{N_A})$, I_V : a subset of $I = \{j | \ell_j \text{ divides } N_A\}$;
Ensure: $\{f'_k | k \in I_V\}$, where $f'_k = tr_{\mathbb{F}_{p^2}/\mathbb{F}_p}((f')^{\prod_{j \in I_V \setminus \{k\}} \ell_j})$.

- 1: $n' \leftarrow \#I_V$;
- 2: **if** $n' = 1$ **then**
- 3: **return** $\{f'\}$;
- 4: **end if**
- 5: $m' \leftarrow \lfloor n'/2 \rfloor$;
- 6: Divide I_V into two subsets I_1, I_2 such that $\#I_1 = n' - m'$ and $\#I_2 = m'$;
- 7: $L_1 \leftarrow \prod_{i \in I_2} \ell_i$, $L_2 \leftarrow \prod_{i \in I_1} \ell_i$;
- 8: $left \leftarrow \text{LS}(f', L_1)$; // Algorithm 1
- 9: $right \leftarrow \text{LS}(f', L_2)$; // Algorithm 1
- 10: $r_1 \leftarrow \text{BCE}(left, I_1)$;
- 11: $r_2 \leftarrow \text{BCE}(right, I_2)$;
- 12: **return** $r_1 \cup r_2$.

After that, we check if each of them is equal to 2 or not. Thanks to Lemma 1, we can deduce whether $(f')^{N_A/\ell_k}$ is equal to 1, and thus its order can be determined.

In a nutshell, we present Algorithm 6 to deterministically generate V .

Remark 4. During the torsion basis generation, the first batch cofactor multiplication of U in Line 3 of Algorithm 3 and the first pairing computation in Line 2 of Algorithm 6 consume large computational resources. To eliminate these two expensive parts for Alice, Bob could send her the initial I_U (in Line 4 of Algorithm 3) and I_V (in Line 4 of Algorithm 6). They can be translated into two $(t+1)/2$ -bit strings. It would be a trade-off between the compressed key size and efficiency.

4.2 Discrete logarithm computation

Different from the case we handle in SIDH, one should compute discrete logarithms in the multiplicative group μ_{N_A} where $N_A = \ell_1 \cdots \ell_3 \cdots \ell_t$. Since N_A is smooth, one can use the Pohlig-Hellman algorithm [38] to transfer a discrete logarithm in μ_{N_A} to discrete logarithms in the groups μ_{ℓ_j} with $j \in I = \{j | \ell_j \text{ divides } N_A\}$, and finally use the Chinese Remainder Theorem to recombine.

Algorithm 6 GenerationV: deterministically generate a point of order N_A such that $\langle U, V \rangle = E_B[N_A]$

Require: E_B/\mathbb{F}_{p^2} : a supersingular curve, $I : \{j|\ell_j \text{ divides } N_A\}$, U and $\{U_k\}$: output of Algorithm 3;

Ensure: A point $V \in E_B(\mathbb{F}_{p^2})$ of order N_A such that $\langle U, V \rangle = E_B[N_A]$.

```

1: Deterministically generate a point  $V \in E_B(\mathbb{F}_{p^2})$  using Elligator;
2:  $f' \leftarrow \text{tr}_{\mathbb{F}_{p^2}/\mathbb{F}_p}(e_{N_A}(U, V))$ ;
3:  $\{f'_j\} \leftarrow \text{BCE}(f', I)$ ; // Algorithm 5
4:  $I_V \leftarrow \{j_k | f'_{j_k} = 2\}$ ;
5: while  $I_V \neq \emptyset$  do
6:   Deterministically generate a point  $V' \in E_B(\mathbb{F}_{p^2})$  using Elligator;
7:    $U' \leftarrow \sum_{j_k \in I_V} U_{j_k}$ ,  $L \leftarrow \prod_{j_k \in I_V} \ell_{j_k}$ ;
8:    $f' \leftarrow \text{tr}_{\mathbb{F}_{p^2}/\mathbb{F}_p}(e_L(U', V'))$ ;
9:    $\{f'_{j_k}\} \leftarrow \text{BCE}(f', I_V)$ ; // Algorithm 5
10:  if  $f'_{j_k} \neq 2$  for some  $j_k$  then
11:     $V' \leftarrow [\prod_{j \in I \setminus I_V} \ell_j]V'$ ;
12:     $\{V'_{j_k}\} \leftarrow \text{BCM}(V', I_V)$ ; // Algorithm 4
13:  end if
14:  for each  $j_k \in \{j_k | f'_{j_k} \neq 2\}$  do
15:     $V \leftarrow V + V'_{j_k}$ ;
16:  end for
17:   $I_V \leftarrow \{j_k | f'_{j_k} = 2\}$ ;
18: end while
19:  $V \leftarrow [2fN_B]V$ ;
20: return  $V$ .

```

Firstly, we compute $h_i^{N_A/\ell_j}$ with $j \in I$ and $i = 1, 2, 3, 4$ using a divide-and-conquer approach. Note that this step is accelerated with the help of Lucas sequences [41, Section 3], as we proposed in Algorithm 7.

After that, for each $j \in I$ we compute the discrete logarithms of $h_i^{N_A/\ell_j}$ to the base $h_0^{N_A/\ell_j}$, where $h_0 = e_{N_A}(P_A, Q_A)^{N_B}$. Since P_A and Q_A are fixed, all the values $h_0^{N_A/\ell_j}$ can be precomputed to accelerate the performance. From Equation (3), it is clear that $d_i = \log_{h_0} h_i$, $c_i = -\log_{h_0} h_{i+2}$, $i = 0, 1$. For each $j \in I = \{j|\ell_j \text{ divides } N_A\}$, let $c_i^{(j)} = c_i \bmod \ell_j$, $d_i^{(j)} = d_i \bmod \ell_j$, $i = 0, 1$.

Finally, from $d_i^{(j)}$, $c_i^{(j)}$ with $j \in I$ we respectively recover $d_i = \log_{h_0} h_i$, $c_i = -\log_{h_0} h_{i+2}$, $i = 0, 1$. This step is fast with the help of the Chinese Remainder Theorem.

Algorithm 8 is the pseudocode summarizing our ideas to compute discrete logarithms.

4.3 Further compression

In this subsection we propose an approach to overcome the issue mentioned in Remark 1. The technique further reduces the public key size and simultaneously

Algorithm 7 BCEA: Batch cofactor exponentiation in μ_{N_A}

Require: $h' \in \mu_{N_A}$, I' : a subset of $I = \{j|\ell_j \text{ divides } N_A\}$;

Ensure: $\{h'_1, h'_2, \dots, h'_{n'}\}$, where $h'_k = \left((h')^{\prod_{j \in I' \setminus \{k\}} \ell_j} \right)$ and $n' = \#I'$.

- 1: **if** $n' = 1$ **then**
- 2: **return** $\{h'\}$;
- 3: **end if**
- 4: $m' \leftarrow \lfloor n'/2 \rfloor$;
- 5: Divide I' into two subsets I_1, I_2 such that $\#I_1 = n' - m'$ and $\#I_2 = m'$;
- 6: $L_1 \leftarrow \prod_{i \in I_2} \ell_i$, $L_2 \leftarrow \prod_{i \in I_1} \ell_i$;
- 7: $left \leftarrow \text{ELS}(h', L_1)$; // Algorithm 2
- 8: $right \leftarrow \text{ELS}(h', L_2)$; // Algorithm 2
- 9: $r_1 \leftarrow \text{BCEA}(left, I_1)$;
- 10: $r_2 \leftarrow \text{BCEA}(right, I_2)$;
- 11: **return** $r_1 \cup r_2$.

Algorithm 8 Discrete logarithm computation

Require: $I: \{j|\ell_j \text{ divides } N_A\}$; h_1, h_2, h_3, h_4 : the values computed in Equation (4);

Ensure: c_0, c_1, d_0, d_1 : Integers in $\{0, 1, \dots, N_A - 1\}$ such that $h_1 = h_0^{d_0}$, $h_2 = h_0^{d_1}$, $h_3 = h_0^{-c_0}$ and $h_4 = h_0^{-c_1}$.

- 1: **for** $k \in \{1, 2, 3, 4\}$ **do**
- 2: $\{h_k^{(j)}\} \leftarrow \text{BCEA}(h_k, I)$; // Algorithm 7
- 3: **end for**
- 4: **for** $k \in \{1, 2\}$ **do**
- 5: **for** each $j \in I$ **do**
- 6: find $d_k^{(j)}$ such that $h_k^{(j)} = \left(h_0^{(j)} \right)^{d_k^{(j)}}$, find $c_k^{(j)}$ such that $h_{k+2}^{(j)} = \left(h_0^{(j)} \right)^{-c_k^{(j)}}$;
- 7: **end for**
- 8: Use the Chinese remainder theorem to compute $d_k \bmod N_A$ and $c_k \bmod N_A$ such that $d_k \equiv d_k^{(j)} \bmod \ell_j$ and $c_k \equiv c_k^{(j)} \bmod \ell_j$ with $j \in I$;
- 9: **end for**
- 10: **return** c_0, c_1, d_0, d_1 .

improve the performance of discrete logarithm computation. We also prove that the modification does not affect the security of compressed M-SIDH.

As mentioned in Remark 1, none of s_i is invertible in $\mathbb{Z}/N_A\mathbb{Z}$ when none of h_i is a generator of μ_{p+1} . Nevertheless, from Equation (2) we have

$$\begin{bmatrix} U_j \\ V_j \end{bmatrix} = \begin{bmatrix} c_0^{(j)} & d_0^{(j)} \\ c_1^{(j)} & d_1^{(j)} \end{bmatrix} \begin{bmatrix} [N_A/\ell_j]\phi_B(P_A) \\ [N_A/\ell_j]\phi_B(Q_A) \end{bmatrix}. \quad (10)$$

where $c_i^{(j)} = c_i \bmod \ell_j$, $d_i^{(j)} = d_i \bmod \ell_j$, $i = 0, 1$ and $j \in I = \{j|\ell_j \text{ divides } N_A\}$. Note that $\langle U, V \rangle = \langle \phi_B(P_A), \phi_B(Q_A) \rangle = E_B[N_A]$ and ℓ_j is prime. Therefore, either $d_0^{(j)}$ or $d_1^{(j)}$ is invertible, i.e., either $h_1^{N_A/\ell_j}$ or $h_2^{N_A/\ell_j}$ is a generator of μ_{ℓ_j} . From this observation, we can compute the discrete logarithms as follows.

Firstly, compute $h_i^{N_A/\ell_j}$ with $j \in I$ and $i = 1, 2, 3, 4$ using a divide-and-conquer approach. This step can be done by Algorithm 7.

Secondly, for each $j \in I$ we check whether $h_1^{N_A/\ell_j}$ is the generator of μ_{ℓ_j} . Note that it is equivalent to check whether $h_1^{N_A/\ell_j}$ is equal to 1 since ℓ_j is a prime. If $h_1^{N_A/\ell_j}$ generates μ_{ℓ_j} , compute discrete logarithms of $h_2^{N_A/\ell_j}, h_3^{N_A/\ell_j}, h_4^{N_A/\ell_j}$ to the base $h_1^{N_A/\ell_j}$. Otherwise, we can deduce that $h_2^{N_A/\ell_j}$ is a generator and then compute discrete logarithms of $h_3^{N_A/\ell_j}, h_4^{N_A/\ell_j}$ to the base $h_2^{N_A/\ell_j}$. Suppose that $S_i^{(j)}$ $i = 1, 2, 3$ are the solutions and the label $label_j$ is used to mark whether $h_1^{N_A/\ell_j}$ is the generator. Hence, we have

$$(S_1^{(j)}, S_2^{(j)}, S_3^{(j)}, label_j) = \begin{cases} ((d_0^{(j)})^{-1}d_1^{(j)}, -(d_0^{(j)})^{-1}c_0^{(j)}, -(d_0^{(j)})^{-1}c_1^{(j)}, 1), & \text{if } d_0^{(j)} \neq 0, \\ (1, -(d_1^{(j)})^{-1}c_0^{(j)}, -(d_1^{(j)})^{-1}c_1^{(j)}, 0), & \text{otherwise.} \end{cases} \quad (11)$$

Thanks to the Chinese Remainder Theorem, one can obtain $S_i \bmod N_A$ such that $S_i \equiv S_i^{(j)} \bmod \ell_j$ for each $j \in I$.

Using the above method, the compressed key is $(E_B, S_1, S_2, S_3, label)$, where

$$label = label_1 + label_3 \cdot 2 + \dots + label_t \cdot 2^{(t-1)/2}. \quad (12)$$

Algorithm 9 illustrates our new approach to compute the discrete logarithms.

Proposition 4. *After applying Algorithm 9 and modifying the compressed key, one can still compress the public key or decompress the compressed key successfully.*

Proof. It is obvious that one can compress the public key successfully. It remains to show how to generate a kernel generator G_A of the group $\langle \phi_B(P_A) + [sk_A]\phi_B(Q_A) \rangle = \langle [d_1 - c_1 \cdot sk_A]U + [-d_0 + c_0 \cdot sk_A]V \rangle$ according to $(E_B, S_1, S_2, S_3, label)$.

Using Algorithms 3 and 6, one can deterministically generate U and V such that $\langle U, V \rangle = E_B[N_A]$ and then construct

$$S_4^{(j)} \equiv 1 \bmod \ell_j \text{ if } label_j = 1, \text{ or } S_4^{(j)} \equiv 0 \bmod \ell_j \text{ otherwise.} \quad (13)$$

Utilizing the Chinese Remainder Theorem, the value $S_4 \bmod N_A$ such that $S_4 \equiv S_4^{(j)} \bmod \ell_j$ can be obtained according to Equation (13). Let

$$G_A = [S_1 + S_3 \cdot sk_A]U - [S_4 + S_2 \cdot sk_A]V.$$

Now we show that G_A is a generator of $\langle \phi_B(P_A) + [sk_A]\phi_B(Q_A) \rangle$. It is equivalent to show that for each $k \in I$,

$$\langle [N_A/\ell_k]G_A \rangle = \langle [d_1 - c_1 \cdot sk_A]U_k + [-d_0 + c_0 \cdot sk_A]V_k \rangle, \quad (14)$$

where $U_k = [N_A/\ell_k]U$ and $V_k = [N_A/\ell_k]V$. If $label_j = 1$, then $S_4 \equiv 1 \bmod \ell_j$ and hence

$$[N_A/\ell_k]G_A = [S_1 + S_3 \cdot sk_A]U_k - [1 + S_2 \cdot sk_A]V_k.$$

Algorithm 9 Another approach to compute discrete logarithms

Require: I : $\{j | \ell_j \text{ divides } N_A\}$; h_1, h_2, h_3, h_4 : the values computed in Equation (4);
Ensure: $label$: A $(t+1)/2$ -bit integer defined in Equation (12); S_1, S_2, S_3 : Integers in $\{0, 1, \dots, N_A - 1\}$, which satisfy $S_i \equiv S_i^{(j)} \pmod{\ell_j}$ ($S_i^{(j)}$ are defined in Equation (11)) for each $j \in I$.

- 1: **for** $k \in \{1, 2, 3, 4\}$ **do**
- 2: $\{h_k^{(j)}\} \leftarrow \text{BCEA}(h_k, I)$; // Algorithm 7
- 3: **end for**
- 4: **for each** $j \in I$ **do**
- 5: **if** $h_1^{(j)} \neq 1$ **then**
- 6: **for each** $k \in \{1, 2, 3\}$ **do**
- 7: find $S_k^{(j)}$ such that $h_{k+1}^{(j)} = (h_1^{(j)})^{S_k^{(j)}}$;
- 8: **end for**
- 9: **else**
- 10: $S_1^{(j)} = 1$;
- 11: **for each** $k \in \{2, 3\}$ **do**
- 12: find $S_k^{(j)}$ such that $h_{k+1}^{(j)} = (h_2^{(j)})^{S_k^{(j)}}$;
- 13: **end for**
- 14: **end if**
- 15: **end for**
- 16: **for each** $k \in \{1, 2, 3\}$ **do**
- 17: Use the Chinese remainder theorem to compute $S_k \pmod{N_A}$ such that $S_k \equiv S_k^{(j)} \pmod{\ell_j}$ with $j \in I$;
- 18: **end for**
- 19: $label \leftarrow \sum_{j \in I} label_j \cdot 2^{(j-1)/2}$;
- 20: **return** $S_1, S_2, S_3, label$.

Note that

$$\begin{aligned} & [S_1 + S_3 \cdot sk_A]U_k - [1 + S_2 \cdot sk_A]V_k \\ &= [S_1^{(j)} + S_3^{(j)} \cdot sk_A]U_k - [S_1^{(j)} + S_2^{(j)} \cdot sk_A]V_k \\ &= [(d_0^{(j)})^{-1}d_1^{(j)} - (d_0^{(j)})^{-1}c_1^{(j)} \cdot sk_A]U_k - [1 - (d_0^{(j)})^{-1}c_0^{(j)} \cdot sk_A]V_k \\ &= [(d_0^{(j)})^{-1}] \cdot \left([d_1^{(j)} - c_1^{(j)} \cdot sk_A]U_k + [-d_0^{(j)} + c_0^{(j)} \cdot sk_A]V_k \right). \end{aligned}$$

In other words, we have

$$[N_A/\ell_k]G_A \in \langle [d_1 - c_1 \cdot sk_A]U_k + [-d_0 + c_0 \cdot sk_A]V_k \rangle$$

when $S_4^{(j)} = 1$. Similarly, we can deduce that $[N_A/\ell_k]G_A$ and $[d_1 - c_1 \cdot sk_A]U_k + [-d_0 + c_0 \cdot sk_A]V_k$ are linearly dependent when $S_4^{(j)} = 0$. Therefore, the point G_A satisfies Equation (14).

Now we show that the modification we propose in this subsection does not affect the security of compressed M-SIDH. We prove that Problem 2 is the problem underlying the security of compressed M-SIDH, and compressed M-SIDH is secure as long as M-SIDH is secure, i.e., Problem 1 is hard.

Problem 2. Let $N_A = \ell_0 \ell_2 \cdots \ell_{t-1}$ and $N_B = \ell_1 \ell_3 \cdots \ell_t$ be two smooth integers, and f be a small cofactor such that $p = N_A N_B f - 1$ is a prime, where $N_A \approx N_B$. Let E_0/\mathbb{F}_{p^2} be a supersingular elliptic curve such that $\#E_0(\mathbb{F}_{p^2}) = (p+1)^2 = (N_A N_B f)^2$. Suppose that $E_0[N_A] = \langle P_A, Q_A \rangle$. Let $\phi_B : E_0 \rightarrow E_B$ be a uniformly random N_B -isogeny and let b be a uniformly random element of $\mathbb{Z}/N_A\mathbb{Z}^\times$. Given $E_0, P_A, Q_A, E_B, [b]\phi_B(P_A)$ and $[b]\phi_B(Q_A)$, compute ϕ_B .

Proposition 5. *After applying Algorithm 9 and modifying the public key, compressed M-SIDH is secure whenever Problem 1 is hard.*

Proof. From the compressed key $(E_B, S_1, S_2, S_3, \text{label})$, we can recover S_4 using the Chinese Remainder Theorem, thus we are able to compute

$$\begin{aligned} P'_A &= [S_1]U_A - [S_4]V_A = [b]\phi_B(P_A), \\ Q'_A &= [S_3]U_A - [S_2]V_A = [b]\phi_B(Q_A), \end{aligned}$$

where $b \in \mathbb{Z}/N_A\mathbb{Z}^\times$ satisfies

$$\begin{cases} bd_0^{(j)} \equiv 1 \pmod{\ell_j}, \text{ if } \text{label}_j = 1, \\ bd_1^{(j)} \equiv 1 \pmod{\ell_j}, \text{ otherwise.} \end{cases}$$

Note that $d_0^{(j)} \pmod{N_A} \in \{-1, 1\}$ and $d_1^{(j)} \pmod{N_A} \in \{-1, 1\}$ do not always hold. Using the Chinese Remainder Theorem, we can deduce that $b^2 \pmod{N_A}$ is not always equal to 1. On the other hand, it is clear that one can also compress the public key successfully according to Proposition 4. Therefore, the problem underlying the security of compressed M-SIDH is Problem 2.

The main difference between Problem 1 and Problem 2 is that the former one has an additional restriction that $b \in \mu_2(N_A)$. Indeed, according to [22, Section 3.1], one can execute a discrete logarithm computation of $e_{N_A}([b]\phi_B(P_A), [b]\phi_B(Q_A))$ to the base $e_{N_A}(P_A, Q_A)$ to obtain $b^2 \pmod{N_A}$. Note that it is easy to solve the discrete logarithm since N_A is smooth. After that, one can scale the torsion points by one square root of $b^2 \pmod{N_A}$ to transfer Problem 2 to Problem 1. Therefore, Problem 2 and Problem 1 are equivalent. This ends the proof.

Compared to the former method in Section 4.2, the new method not only further compresses the key but performs better. The main reason is that the latter method saves at least one discrete logarithm in μ_{ℓ_j} for each $j \in I$. Furthermore, it saves considerable storage for precomputation since there is no need to compute discrete logarithms to the base h_0 .

4.4 Section summary

In this subsection, we summarize our approach to compress the public key of M-SIDH from $6 \log(p)$ bits to $3.5 \log(p)$ bits, using all the techniques proposed in this section. A review of the key decompression is also presented. Finally, we briefly describe how to apply our techniques to benefit other isogeny-based protocols.

The optimized approach to compress the key

1. Torsion basis generation: Execute Algorithm 3 to deterministically generate a point $U_A \in E_B(\mathbb{F}_{p^2})$ of order N_A , and then use Algorithm 6 to deterministically generate V_A such that $\langle U_A, V_A \rangle = E_B[N_A]$;
2. Pairing computation: Compute the following four reduced Tate pairings:

$$\begin{aligned} h_1 &= e_{N_A}(\phi_B(P_A), U_A), \quad h_2 = e_{N_A}(\phi_B(P_A), V_A), \\ h_3 &= e_{N_A}(\phi_B(Q_A), U_A), \quad h_4 = e_{N_A}(\phi_B(Q_A), V_A); \end{aligned}$$

3. Discrete logarithm computation: Using Algorithm 9, compute integers $S_1, S_2, S_3 \in \{0, 1, \dots, N_A - 1\}$ and a label $label$, as defined in Equation (12).

The compressed key is $(E_B, S_1, S_2, S_3, label)$, whose size is around $3.5 \log(p)$ bits.

The approach to decompress the key

1. Torsion basis generation: Execute Algorithm 3 to deterministically generate a point $U_A \in E_B(\mathbb{F}_{p^2})$ of order N_A , and then use Algorithm 6 to deterministically generate V_A such that $\langle U_A, V_A \rangle = E_B[N_A]$;
2. Construction of S_4 : From the knowledge of $label$, construct $S_4 \bmod N_A$ such that

$$S_4 \equiv 1 \pmod{\ell_j} \text{ if } label_j = 1, \text{ or } S_4 \equiv 0 \pmod{\ell_j} \text{ otherwise.}$$

As shown in Proposition 4, a generator of $\langle \phi_B(P_A) + [sk_A]\phi_B(Q_A) \rangle$ can be computed by

$$G_A = [S_1 + S_3 \cdot sk_A]U_A - [S_4 + S_2 \cdot sk_A]V_A.$$

Improvement of other isogeny-based protocols Very recently, Basso and Fouosta [7] proposed new SIDH-like protocols called binSIDH and terSIDH. Similar to M-SIDH, the public key of these protocols is of the form (E, P, Q) , where E is a supersingular elliptic curve and $\{P, Q\}$ is a torsion basis of $E[N]$, with N is a highly composite integer. It is obvious that our work can also be extended easily to compress the public key in these SIDH-like schemes.

Besides, our approach to generate full-torsion points has the potential to enhance the performance of non SIDH-like schemes, such as SQALE [14] and dCSIDH [10]. In the implementations of dCSIDH, a full-torsion basis are generated and involved in the public key. It accelerates the performance of the key agreement phase, but increases the computational cost of key generation. Given a supersingular elliptic curve E , one can use Algorithm 3 to generate one full-torsion point $U \in E(\mathbb{F}_p)$, and then apply Algorithm 6 to compute another full-torsion point $V \in E^t(\mathbb{F}_p)$ such that U and V are linearly independent, where E^t is the twist of E . It seems that the improvement is similar to the independent work by Reijnders [39, Section 4.3]. However, the latter one is a probabilistic algorithm, while our algorithms can always generate a full-torsion basis.

5 Implementation Results

In this section, we implement compressed M-SIDH in SageMath (version 9.5) [1] and give our experimental results.

Isogeny computation is the most expensive part of (compressed) M-SIDH. There are mainly two ways to construct the isogeny. One is the traditional Vélu’s formula [44], and the other is a more efficient formula to construct the large degree isogeny [8]. We combine both of them to implement compressed M-SIDH. For small degree isogeny computations we use traditional Vélu’s formula, and use the method proposed in [8] to compute the large degree isogeny.

Based on the code¹ from [8], we give a proof-of-concept implementation of compressed M-SIDH in SageMath. Our code is available at

<https://github.com/CompressedMSIDH/CompressedMSIDH>.

Table 1 reports the performance of the key generation phase. For discrete logarithm computation we apply the method proposed in Section 4.3.

Procedure	Alice	Bob
Isogeny Computation	304.67s	305.89s
Torsion Basis Generation	18.00s	18.81s
Pairing Computation	15.75s	15.66s
Discrete Logarithm Computation	5.68s	5.61s
Total Cost (the whole key generation phase)	344.10s	345.97s

Table 1. Experimental results of key generation of Alice in compressed M-SIDH for the NIST-1 level of security.

As shown in Table 1, isogeny computation dominates the cost of key generation. One may try to utilize several techniques proposed in the literature to speed up the compressed M-SIDH implementation. We adapt the technique proposed in [30] to recover the Montgomery coefficient of the codomain of the isogeny, which offers a significant speedup to isogeny computation. Besides, there are several works on the optimizations of CSIDH [12]. For example, the approach [15] to find an optimal strategy of CSIDH can be easily extended to the isogeny computation of M-SIDH. It is also possible to improve the performance by changing the permutation of the ℓ_j -isogeny computation [26]. The improvement of large degree isogeny computation is explored by [3].

Torsion basis generation and pairing computation are the efficiency bottlenecks of public-key compression in M-SIDH. The computational cost of discrete logarithm computation is approximately one third of that of torsion basis generation. We leave the exploration of the faster implementation of compressed SIDH-like schemes for future work.

¹ <https://velusqrt.isogeny.org/>

6 Conclusion

In this paper, we took M-SIDH as an instance to demonstrate how to compress the public key in new SIDH-like schemes. We proposed compressed M-SIDH, reducing the public key size from $6 \log_2 p$ bits to around $3.5 \log_2 p$ bits, and proved that compressed M-SIDH is secure as long as M-SIDH is secure. In addition, several novel techniques were proposed to accelerate the performance.

It should be noted that some techniques proposed in this paper can optimize other isogeny-based cryptosystems. Our approach to compress the key also applies to other SIDH-like protocols. The implementation of (compressed) M-SIDH is not so efficient now because of the huge characteristic of the base field and expensive isogeny computation, but we believe that the techniques developed in this work would be more attractive with further research on SIDH-like schemes, including binSIDH and terSIDH. In addition, our method for torsion basis generation can improve finding full-torsion points in non SIDH-like protocols, such as SQALE and dCSIDH.

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